3      the assumed-movement pattern includes video data showing virtual

4      poles arranged on the outer edge of the vehicle movement area.

1      9.    (Amended) The driving-operation assist according to [any one

2      of] claim[s] 6 [to 8], characterized in that

3      the synthetic-image generating means superimposes current-position

4      data serving as video data showing an area in which the vehicle is present, on the

5      circumferential-state image to generate the synthetic image.

1      11.    (Amended) The driving-operation assist according to [any one

2      of] claim[s] 6 [to 10], characterized in that when actual driving operations

3      corresponding to the above predetermined series of driving operations are started,

4      the synthetic-image generating means thereafter fixes the positional

5      relation between the assumed-movement pattern and the circumferential-state

6      image at the point of time when the actual driving operations are started and

7      generates the synthetic image.

1      14.    (Amended) The driving-operation assist according to [any one

2      of] claim[s] 6 [to 13], characterized in that

3      final-position inputting means for inputting a final position which is

4      a position of the vehicle at end of the movement and start-position determining

5      means for obtaining a start position which is a position at start of the movement

6      corresponding to the input final position in accordance with the assumed-

7      movement pattern are included, and

8      the synthetic-image generating means superimposes the input final

9      position and the start position corresponding to the input final position on the

10      circumferential-state image to generate the synthetic image.

1      16.    (Amended) The driving-operation assist according to any one of

2      claims 1 to [15]4, characterized in that

3      assumed-movement-pattern storing means is included which holds

4      data relating to the above predetermined series of driving operations and holds

5    assumed-movement data including at least the assumed-movement pattern.

1            18. (Amended) The driving-operation assist according to claim 16

2    [or 17], characterized in that pattern correcting means is included which is able to

3    update and correct the content of the assumed-movement pattern held in the

4    assumed-movement-pattern storing means.

1            21. (Amended) The driving-operation assist according to [any one

2    of] claim[s] 16 [to 20], characterized in that the assumed-movement data includes

3    time-series data showing a relationship between a movement distance and a

4    steering angle of the steering wheel of the vehicle.

1            23. (Amended) The driving-operation assist according to [any one

2    of] claim[s] 11 [to 13 or claim 22], characterized in that operation-start detecting

3    means is included which automatically detects that actual driving operations

4    corresponding to the above predetermined series of driving operations are started

5    through an input from a driver or a predetermined driving operation.

1            24. (Amended) The driving-operation assist according to [any one

2    of] claim[s] 5 [to 23], characterized in that

3            when the viewpoint converting means changes the predetermined

4    viewpoint, the viewpoint converting means fixes the predetermined viewpoint to

5    the vehicle before the actual driving operations corresponding to the

6    predetermined series of driving operations are started and changes the

7    predetermined viewpoint to a point fixed to the three-dimensional space after the

8    actual driving operations corresponding to the predetermined series of driving

9    operations are started.

1            26. (Amended) The driving-operation assist according to any one of

2    claims 1 to [5]4, characterized in that the assumed-movement pattern includes

3    video data showing a circumscribed area on a space through which the vehicle

4    passes when the predetermined series of driving operations are performed.

1            29. (Amended) The driving-operation assist according to any one of

2 claims 1 to [5]4, characterized in that the assumed-movement patterns respectively

3 include a change from backward movement to forward movement or from forward

4 movement to backward movement in the predetermined series of driving

5 operations

30. (Amended) The driving-operation assist according to any one of

claims 1 to [5]4, characterized in that obstacle inputting means is included which

is able to input a position of an obstacle area in an image to displaying means for

displaying the synthetic image from a driver.

1 33. (Amended) A recording medium characterized by storing a

2 program of making a computer execute all of some of functions of each means of

3 any one of claims 1 to [32]4.

1 34. (Newly Added) The driving-operation assist according to claim

2 12, characterized in that operation-start detecting means is included which

3 automatically detects that actual driving operations corresponding to the above

4 predetermined series of driving operations are started through an input from a

5 driver or a predetermined driving operation.

1 35. (Newly Added) The driving-operation assist according to

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2 claim 13, characterized in that operation-start detecting means is included

3 which automatically detects that actual driving operations corresponding to the

4 above predetermined series of driving operations are started through an input

5 from a driver or a predetermined driving operation.

1      36. (Newly Added) The driving-operation assist according to

2 claim 22, characterized in that operation-start detecting means is included

3 which automatically detects that actual driving operations corresponding to the

4 above predetermined series of driving operations are started through an input

5 from a driver or a predetermined driving operation.
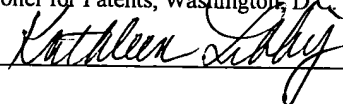
Respectfully Submitted,

Allan Ratner, Reg. No. 19,717
Jack L. Jankovitz, Reg. No. 42,690
Attorneys for Applicants

JJJ/ap
Suite 301
One Westlakes, Berwyn
P.O. Box 980
Valley Forge, PA 19482-0980
(610) 407-0700

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